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Linear Multiuser Receivers: Effective Interference, Effective Bandwidth and Capacity*

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Abstract

To meet the increasing capacity demand on wireless networks, there have been intense efforts in the past decade on developing multi-user receiver structures which mitigate the interference between users in spread-spectrum and antenna array systems. While much of the research is performed at the physical layer, the capacity of networks with multi-user receivers and the associated power control problems are less well-understood. In this paper, we show that under some conditions, the capacity of a single power-controlled cell for several important receivers can be very simply characterized via a notion of effective bandwidth: the quality-of-service requirements of all the users can be met if and only if the sum of the effective bandwidths of the users is less than the total number of degrees of freedom in the system. The number of degrees of freedom is the processing gain in a spread-spectrum system and the number of antenna elements in an antenna array. The effective bandwidth of a user depends only on its own requirement, expressed in terms of the desired signal-to-interference ratio. Simple effective bandwidth expressions are derived for three linear receivers: the conventional matched filter, the decorrelator and the MMSE receiver. The effective bandwidths under the three receivers serve as a basis for performance comparison.

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1 Introduction

The mobile wireless environment provides several unique challenges to reliable communication not commonly found in wireline networks. These include scarce bandwidth, limited transmit power, interference between users, and time-varying channel conditions. A central problem in the design of wireless networks is how to use the limited resources most efficiently in such adverse environments, in order to meet the quality-of-service requirements of applications in terms of bitrate and loss. To meet these challenges, there have been intense efforts in developing more sophisticated physical layer communication techniques. A significant thrust of work has been on developing multi-user receiver structures which mitigate the interference between users in spread spectrum systems. (See for example [16, 6, 7, 21, 8, 11, 12].) Unlike the conventional matched filter receiver used in the IS-95 CDMA system, these techniques take into account the structure of the interference from other users when decoding a user. Another important line of work is the development of processing techniques in systems with antenna arrays. While spread-spectrum techniques provide frequency diversity to the wireless system, antenna arrays provide spatial diversity, both of which are essentially degrees of freedom through which communication can take place.

Despite significant work done in the area, there is still much debate about the network capacity of the various approaches to deal with multi-user interference in spread-spectrum and multi-antenna systems. One reason is that the networking level problems of resource allocation and power control are less well understood in the context of multi-user techniques than with more traditional multi-access schemes, such as TDMA, FDMA and conventional CDMA systems. For example, much of the previous work on performance evaluation of multiuser receivers focus on their ability to reject worst-case interference (so-called near-far resistance [6]) rather than on their performance in a power-controlled system.

In this paper, we will show that under some conditions, a simple characterization of the network capacity is possible for several important multi-user receivers. The specific scenario is a set of power-controlled mobile users communicating to a receiver (base-station) in a single cell. Assuming that each user's requirement can be expressed in terms of a target signal-to-interference ratio (SIR), we will show that a notion of effective bandwidth can be defined such that the SIR requirements of all the users can be met if and only if the sum of the effective bandwidths of the users is less than the total number of degree of freedom in the system. This result holds asymptotically in the regime where the number of degrees of freedom is large. These degrees of freedom can be provided by the processing gain in a spread-spectrum system or the number of antenna elements in a system with an antenna array. These capacity characterizations are simple in that the effective bandwidth of a user depends only on its own SIR requirement and nothing else.

The effective bandwidth of a user depends on the multi-user receiver employed. Results for three receivers are obtained. They are the minimum mean-square (MMSE) receiver [21, 8, 11, 12], the decorrelator [6, 7], and the conventional matched filter receiver. We
will show that the effective bandwidths are respectively:

\[ e_{\text{mmse}}(\beta) = \frac{\beta}{1 + \beta}, \quad e_{\text{dec}}(\beta) = 1, \quad e_{\text{m}}(\beta) = \beta, \]

where \( \beta \) is the SIR requirement of the user. These effective bandwidth expressions also provides a succinct basis for performance comparison between different receiver structures. In particular, the MMSE receiver occupies a special place as it can be shown to lead to the minimum effective bandwidth among all linear receivers. Moreover, its performance is the least understood about the three receivers, and its analysis is the main thrust of this paper.

To obtain these results, we assumed that the users' signals arrive from random directions. In the context of a spread-spectrum system, this means that each of the users employ random spreading sequences. In the context of an antenna array system, this translates into independent fading from each of the users to each of the receiving antenna element.

Related results on the performance of multiuser receivers under random spreading sequences were obtained independently in [18], presented simultaneously as a conference version [14] of this work. They considered exclusively the single class case where every user has the same received power and same rate requirement, and derived Shannon theoretic performance. In the present paper, our main results are for situations where users have different received powers and possibly different SIR requirements.

The outline of the paper is as follows. In Section 2, we will introduce the basic model of a multi-access spread-spectrum system and the structure of the MMSE receiver. In Section 3, we will present our key result, that in a large system with each user using random spreading sequences, the limiting interference effects under the MMSE receiver can be calculated as if they were additive; to each interferer can be ascribed a level of effective interference that it provides to the user to be decoded. In sections 5 and 6, we apply this result to study the performance under power control and obtain a notion of effective bandwidth. In Section 7, we obtain analogous results for the decorrelating receiver. In Section 8, we show that similar ideas carry through for systems with antenna diversity. Section 9 contains our conclusions.

2 Basic Spread-Spectrum Model and the MMSE Receiver

In a spread-spectrum system, each of the user's information or coded symbols is spread onto a much larger bandwidth via modulation by its own signature or spreading sequence. The following is a sampled discrete-time model for a symbol-synchronous multi-access spread-spectrum system:

\[ Y = \sum_{i=1}^{M} X_i s_i + W, \quad (1) \]
where $X_i \in \mathbb{R}$ and $s_i \in \mathbb{R}^L$ are the transmitted symbol and signature spreading sequence of user $m$ respectively, and $W$ is $N(0, \sigma^2 I)$ background Gaussian noise. The length of the signature sequences is $L$, which one can also think of as the number of degrees of freedom or diversity. The received vector is $Y \in \mathbb{R}^n$. We assume the $X_i$'s are independent and that $E[X_i] = 0$ and $E[X_i^2] = P_i$, where $P_i$ is the received power of user $i$.

Rather than looking at symbol-by-symbol detection, we are interested in the more general problem of demodulation, extracting good estimates of the (coded) symbols of each user as soft decisions to be used by the channel decoder [12]. From this point of view, the relevant performance measure is the signal-to-interference ratio (SIR) of the estimates.

We shall now focus on the demodulation of user 1, assuming that the receiver has already acquired the knowledge of the spreading sequences. In this paper, we shall confine ourselves to the study of linear demodulators, such that the estimates are linear functions of the received vector $Y$. For user 1, the optimal demodulator $c_1$ that generates a soft decision $\hat{X}_1 \equiv c_1^t Y$ maximizing the signal-to-interference ratio (SIR):

$$\beta_1 \equiv \frac{(c_1^t s_1)^2 P_1}{(c_1^t c_1)^2 \sigma^2 + \sum_{i=2}^{M} (c_i^t s_i)^2 P_i}$$

is the MMSE receiver \[8, 11, 12\].

As a comparison, note that the conventional CDMA approach simply matches the received vector to $s_1$, the signature sequence of user 1. This is indeed the optimal receiver when the interference from other users is white. However, in general the multi-access interference is not white and has structure defined by $s_2, s_3, \ldots, s_M$, assumed to be known to the receiver. The MMSE receiver exploits the structure in this interference in maximizing the SIR of user 1.

While there are well-known formulas for the MMSE receiver and its performance, we will describe simple derivations for two equivalent formulas, which provides some geometric insights to the operation of this receiver. Let

$$Z = \sum_{i=2}^{M} X_i s_i + W$$

be the total interference for user 1 from other users and background noise. Then

$$Y = X_1 s_1 + Z$$

If $Z$ were white, then

$$X_{\text{mmse}}(Y) = \frac{s_1^t Y}{s_1^t s_1},$$

\[More precisely, this should be termed the linear least square (LLSE) receiver, since it is only optimal within the class of linear receivers if the $X_i$'s are not Gaussian. In deference to the standard practice in the multiuser detection literature, however, we will call this the MMSE receiver.
which is a projection onto \( s_1 \), i.e. the conventional matched filter. In general, then, we should whiten the interference \( Z \) and then followed by a projection. The covariance matrix of \( Z \) is

\[
K_z = S_1 D_1 S_1^t + \sigma^2 I
\]

where \( S_1 \) is a \( L \) by \( M - 1 \) matrix whose columns are the signature sequences of the other users, and \( D_1 = \text{diag}(P_2, \ldots, P_M) \) is the covariance matrix of \( (X_2, \ldots, X_M)^t \). \( K_z \) is positive definite. Factorize \( K_z = Q^t \Lambda Q \), where \( \Lambda = \text{diag}(\lambda_1, \ldots, \lambda_L) \) is the diagonal matrix of (positive) eigenvalues of \( K_z \), and the columns of \( Q \) are the orthonormal eigenvectors of \( K_z \). The whitening filter is simply \( \Lambda^{-\frac{1}{2}} Q \). Applying this to \( Z \), we get:

\[
\Lambda^{-\frac{1}{2}} Q Y = X_1 \Lambda^{-\frac{1}{2}} Q s_1 + \Lambda^{-\frac{1}{2}} Q Z
\]

The interference is now white. We can then project it along the direction \( \Lambda^{-\frac{1}{2}} Q s_1 \) to get a scalar sufficient statistic for the estimation problem:

\[
R \equiv s_1^t K_z^{-1} Y = (s_1^t K_z^{-1} s_1) X_1 + s_1^t K_z^{-1} Z
\]

Thus, the MMSE demodulator is:

\[
X_{\text{mmse}}(Y) = \frac{1}{s_1^t (S_1 D_1 S_1^t + \sigma^2 I)^{-1} s_1} s_1^t (S_1 D_1 S_1^t + \sigma^2 I)^{-1} Y
\]  

and the signal to interference ratio for user 1 is

\[
SIR_1 = s_1^t (S_1 D_1 S_1^t + \sigma^2 I)^{-1} s_1 P_1
\]  

3 Performance Under Random Spreading Sequences

Eqn. (3) is a formula for the performance of the MMSE receiver, which one can compute for specific choice of signature sequences. However, it is not easy to obtain qualitative insights directly from the formula. For example, the effect of an individual interferer on the SIR for user 1 cannot be seen directly from this formula. In practice, it is often reasonable to assume that the spreading sequences are randomly and independently chosen. (See eg. [4]. For example, they may be pseudorandom sequences, or the users choose their sequences from a large set of available sequences as they are admitted into the network. In this case, the performance of the optimal demodulator can be modeled as a random variable, since it is a function of the spreading sequences. In this section, we will show that, unlike the deterministic case, there is a great deal of analytical information one can obtain about this random performance in a large network. In the development below, we will assume that though the sequences are randomly chosen, they are known to the receiver once they are picked. In practice, this means that the change in the spreading sequences is at a much slower time-scale than the symbol rate so that the receiver has the
time to acquire the sequences. (There are known adaptive algorithms for which this can even be done blindly; see [4].) However, the performance of the MMSE receiver depends on the initial choice of the sequences and hence random.

The model for random sequences: let $s_i = \frac{1}{\sqrt{L}} (V_{i1}, \ldots, V_{iL})^T$, $i=1, \ldots M$. The random variables $V_{ik}$'s are i.i.d., zero mean and variances 1. The normalization by $\frac{1}{\sqrt{L}}$ ensures that $E[\|s_i\|^2] = 1$. In practice, it is common that the entries of the spreading sequences are 1 or $-1$, but we want to keep the model general so that we can later apply our results to problems with other modes of diversity. For technical reasons, we will also make the mild assumption that $E[V_{ik}^4] < \infty$.

Our results are asymptotic in nature, for a large network. Thus, we consider the limiting regime where the number of users are large, i.e. $M \to \infty$. To support a large number of users, it is reasonable to scale up $L$ as well, keeping the number of users per degree of freedom (equivalently, per unit bandwidth), $\alpha \equiv \frac{M}{L}$, fixed. We also assume that as we scale up the system, the empirical distribution of the powers of the users converge to a fixed distribution, say $F(P)$. The following is our main result, giving the asymptotic information about the SIR for user 1.

**Theorem 3.1** Let $\beta_1^{(L)}$ be the (random) SIR of the MMSE receiver for user 1 when the spreading length is $L$. Then $\beta_1^{(L)}$ converges to $\beta_1^*$ in probability as $L \to \infty$, where $\beta_1^*$ is the unique solution to the equation:

$$\beta_1^* = \frac{P_1}{\sigma^2 + \alpha \int_{0}^{\infty} I(P, P_1, \beta_1^*) dF(P)}$$

and

$$I(P, P_1, \beta_1^*) \equiv \frac{PP_1}{P_1 + PP_1^*}$$

Heuristically, this means that in a large system, the SIR $\beta_1$ is deterministic and approximately satisfies:

$$\beta_1 \approx \frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} I(P_i, P_1, \beta_1)}$$

where as before $P_i$ is the received power of user $i$. This result yields an interesting interpretation of the effect of each of the interfering user on the SIR of user 1: for a large system, the total interference can be decoupled into a sum of the background noise and an interference term from each of the other users. (The factor $\frac{1}{L}$ results from the processing gain of user 1.) The interference term depends only on the received power of the interfering user, the received power of user 1 and the attained SIR. It does not depend on the other interfering users except through the attained SIR $\beta_1$. This decoupling is rather surprising.

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\(^2\)This assumption is needed for the current proof to go through but may not be really necessary. A weaker form of regularity may suffice.
since the effect of an interferer depends on the MMSE receiver \( c_1 \), which in turn is a function of the signature sequences and received powers of all the users in the system.

One must be cautioned not to think that this result implies that the interfering effect of the other users on a particular user is additive across users. It is not, since the interference term \( I(P_i, P_1, \beta_1) \) from interferer \( i \) depends on the attained SIR which in turn is a function of the entire system. Due to the following proposition, on the other hand, one can make a related statement.

**Proposition 3.2** The equation

\[
x = \frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} I(P_i, P_1, x)}
\]

has a unique fixed point \( x^* \). For any \( x, x \geq x^* \) if and only if

\[
\frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} I(P_i, P_1, x)} \geq x
\]

**Proof.** Define the function

\[
f(x) = \frac{1}{P_1} \left( \sigma^2 x + \frac{1}{L} \sum_{i=2}^{M} xI(P_i, P_1, x) \right)
\]

\[
= \frac{1}{P_1} \left( \sigma^2 x + \frac{1}{L} \sum_{i=2}^{M} \frac{P_i P_1 x}{P_i + P_1 x} \right)
\]

which we note to be a continuous, increasing function.

To see that a fixed point \( x^* \) exists to (6), we note that \( f(0) = 0 \) and \( f(\infty) = \infty \) so it follows that there must exist a value \( x^* \) satisfying \( f(x^*) = 1 \). But this implies that \( x^* \) is a fixed point of (6).

To see uniqueness, and to prove the rest of the proposition, we note that

\[
x \leq x^* \iff f(x) \leq 1
\]

\[
\iff x \leq \frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} I(P_i, P_1, x)}
\]

and conversely that

\[
x \geq x^* \iff f(x) \geq 1
\]

\[
\iff x \geq \frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} I(P_i, P_1, x)}
\]

\( \square \)
It follows then that to check if the target for user 1's SIR, \( \beta_T \), can be met for a given system of users, it suffices to check the following condition:

\[
\frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} I(P_i, P_1, \beta_T)} \geq \beta_T
\]

Based on this interpretation, it seems justified to term \( I(P_i, P_1, \beta_T) \) as the effective interference of user \( i \) on user 1, at a target SIR of \( \beta_T \).

To gain more insights into this concept of effective interference, it is helpful to compare the situation with that when the conventional matched filter \( s_1 \) is used for the demodulation. For that case, we have the following proposition, in parallel with Theorem 3.1:

**Proposition 3.3** Let \( \beta_{1,MF}^{(L)} \) be the (random) SIR of the conventional matched filter receiver for user 1 when the spreading length is \( L \). Then as \( L, M \to \infty \) with \( \frac{M}{L} \to \alpha \), \( \beta_{1,MF}^{(L)} \) converges in probability to

\[
\beta_{1,MF}^{*} = \frac{P_1}{\sigma^2 + \alpha \int_{0}^{\infty} P dF(P)}
\]

where as before \( F \) is the limiting distribution of the powers of the users.

**Proof.** See appendix C. \( \Box \)

Hence, for large \( L \), the performance of the matched receiver is approximately:

\[
\beta_{1,MF} \approx \frac{P_1}{\sigma^2 + \frac{1}{L} \sum_{i=2}^{M} P_i}
\]

Comparing this expression with eqn. (5), we see that the interference due to user \( i \) is simply \( P_i \) in place of \( I(P_i, P_1, \beta_i) \). Since the matched receiver filter is independent of the signature sequences of the other users, it is not surprising that the interference is linear in the received powers of the interferers. In the case of MMSE receiver, the filter does depend on the signature sequences of the interferers, thus resulting in the interference being a non-linear function of the received power of the interferer. Also, observe that \( I(P_i, P_1, \beta_t) < P_i \), which is expected since the MMSE receiver maximizes the SIR among all linear receivers. But more importantly, we see that while for the conventional receiver, the interference grows unbounded as the received power of the interferer increases, we see that for the MMSE receiver, the effective interference from user \( i \) is bounded and approaches \( \frac{P_i}{\beta_i} \) as \( P_i \) goes to infinity. Thus, while the SIR of the matched filter receiver goes to zero for large interferers' powers, the SIR of the MMSE receiver does not. This is the well-known near-far resistance property of the MMSE receiver [8]. The intuition is that as the power of an interferer grows to infinity, the MMSE receiver will null out its signal. While the near-far resistance property has been reported by previous authors, Theorem 3.1 goes beyond that as it not only quantifies the worst-case performance (i.e.
large interferer’s power) but also the performance for all finite values of the interference. This is useful for example in situations when power control is exercised, as we will turn to in the next section.

In general, we have no explicit solution for the SIR $\beta_1^*$ in eqn. (4). However, for the special case when the received powers of all users are the same, the equation is quadratic in $\beta_1^*$ and a simple solution is obtained:

$$\beta_1^* = \frac{(1 - \alpha)P}{2\sigma^2} - \frac{1}{2} + \sqrt{\frac{(1 - \alpha)^2P^2}{4\sigma^4} + \frac{(1 + \alpha)P}{2\sigma^2} + \frac{1}{4}}$$

(8)

We see that the $\beta_1^*$ is positive for all values of $\alpha$, and approaches 0 as $\alpha$, the number of users per degree of freedom, goes to infinity.

To get a sense of the convergence of the random SIR to the asymptotic limit in the equal received power case, Fig. 1 compares the actually realized SIR’s from randomly generated spreading sequences to the asymptotic limit (8). For different spreading lengths and for each value of $\alpha$, 100 samples of realized SIR’s for user 1 are obtained from randomly generated +1 and −1 spreading sequences. One sees that as the processing gain increases, the spread around the asymptotic becomes more narrow, to about 1 or 2 dB when $L = 128$. Note however that for a fixed processing gain, the spread does not get smaller as the number of users increases, which means that the relative spread is large when the SIR is low. Fig. 2 plots the SIR’s attained across users for a single realization of the random spreading sequences. The processing gain $L = 128$ and the number of users is 80. Again, there is a spread of about 1 db around the asymptotic limit.

Two performance measures commonly used in the literature for multiuser receivers are their efficiency and their asymptotic efficiency [17]. In the context of linear receivers, the efficiency for user 1 is defined to be the ratio of the achieved SIR to the SIR when there is no interferer and only background noise. For the MMSE receiver with random spreading sequences and equal received power for all users, this is given by:

$$\beta_1^*\sigma^2 \frac{P}{P}$$

where $\beta_1^*$ is given by the above expression. The asymptotic efficiency $\eta_1$ is the limiting efficiency as the background noise goes to zero. If $\alpha \leq 1$, this is given by:

$$\eta_1 := \lim_{\sigma \to 0} \frac{\beta_1^*\sigma^2}{P} = 1 - \alpha$$

For $\alpha > 1$, the limiting SIR is positive but bounded:

$$\lim_{\sigma \to 0} \beta_1^* = \frac{1}{\alpha - 1}$$

(9)

and so the asymptotic efficiency is 0.
Figure 1: Randomly generated SIR's for user 1 compared to asymptotic limit eqn. (8), for $L = 32, 64, 128$. Here, $\frac{P}{\sigma^2} = 20 dB$. 
Figure 2: Randomly generated SIR's across users for one realization of the spreading sequences. Here, spreading length $L = 128$, number of users $M = 80$ and $\frac{P}{\sigma^2} = 20dB$. 
4 Proof of Main Theorem

We will now prove our main result, Theorem 3.1. It hinges on a result about the limiting
eigenvalue distribution of large matrices whose elements are random variables. Let \( X_{ij} \)
be an infinite array of i.i.d. complex-valued random variables with variances 1, and \( U_i \)
be a sequence of real-valued random variables. Let \( A_{n,m} \) be an \( n \times m \) matrix, whose \((i,j)\)th
entry is \( \frac{X_{ij}}{\sqrt{n}} \). Let \( T_m \) be an \( m \times m \) diagonal matrix whose diagonal entries are \( U_1, \ldots, U_m \); we assume that as \( m \to \infty \), the empirical distribution of these entries converge almost
surely to a non-random limit \( F \).

The matrix \( A_{n,m}T_mA_{n,m}^H \) (\( A^H \) is the complex conjugate transpose of \( A \)) is \( n \times n \)
Hermitian and has real non-negative eigenvalues \( \lambda_1^{(n)}, \ldots, \lambda_n^{(n)} \). Let \( G_n(\lambda) \) be the empirical
distribution of the eigenvalues; since the eigenvalues are random, so is \( G_n \). (The empirical
distribution of the eigenvalues depends on the realization of the random entries of \( A \) and
\( T \).) The following theorem due to Silverstein and Bai [13], which is a strengthening of
an earlier result by Marcenko and Pastur [10], gives the asymptotic behavior of \( G_n \) as \( n \)
and \( m \) grow. The solution is in terms of Stieltjes transforms, where for any distribution
\( G \) is defined as:

\[
m_G(z) = \int \frac{1}{\lambda - z} dG(\lambda)
\]

for \( z \in C^+ \equiv \{ z \in C : \text{Im}z > 0 \} \).

**Theorem 4.1** As \( n,m \to \infty \) such that \( \frac{m}{n} \to \alpha > 0 \), then almost surely \( G_n \) converges
in distribution to a non-random limit \( G^* \). The Stieltjes transform \( m(z) \) of the limit \( G^* \)
satisfies the following equation:

\[
m(z) = \frac{1}{-z + \alpha \int \frac{x dF(x)}{1 + rm(z)}}
\]

for all \( z \in C^+ \).

The above theorem says that the empirical distribution of the eigenvalues for large
random matrices looks the same for almost all realizations of the entries. Eqn. (10) gives
a functional equation for the Stieltjes transform of the limit; in general, it cannot be
solved explicitly.

Applying this result to the covariance matrix \( K_z = S_1D_1S_1^T + \sigma^2I \) of the interference,
we see that in a large system with random signature sequences, the spectrum of the
interference is essentially deterministic. Moreover, the deterministic spectrum is colored
and not white. This is perhaps a little surprising, as one may expect the aggregate
interference to get whiter and whiter as we have more interferers in the system. However,
one must bear in mind that the number of degrees of freedom (dimension of the space) is
also increasing, fixing the number of interferers per degree of freedom. Theorem 4.1 tells
us that these two effects balance each other and yields a colored spectrum in the limit.
As a consequence, the MMSE receiver outperforms the conventional matched filter, even in the limit.

Theorem 4.1 gives the asymptotic distribution of the eigenvalues of the covariance matrix $K_z$. However, this is in general not enough for characterizing the SIR performance for user 1, as that depends on the position of $s_1$ relative to the eigenvectors of $K_z$. This can be seen by writing $K_z = U^\dagger \Lambda U$ where $\Lambda$ is diagonal and $U$ is orthogonal, so that the SIR for user 1 is given by

$$\beta_1 = P_1 s_1 K_z^{-1} s_1 = P_1 (U s_1)^\dagger \Lambda^{-1} (U s_1).$$

However, the following lemma shows that the distribution of the eigenvectors is asymptotically irrelevant since for large spreading length, $s_1$ looks “white” in any coordinate system, in the sense of containing about the same amount of energy in each direction.

**Lemma 4.2** Let $Q$ be a random $m$ by $n$ matrix ($m < n$) such that every realization consists of orthonormal rows. Let $X = (V_1, \ldots, V_n)^\dagger$ where the $V_i$'s are i.i.d. random variables independent of $Q$, $E[V_i] = 0$, $E[V_i^2] = 1$ and $E[V_i^4] < \infty$. Then for any $\epsilon > 0$,

$$\Pr \left[ \left| \frac{\|QX\|^2}{n} - \frac{m}{n} \right| > \epsilon \right] < \frac{C}{n}$$

for some constant $C$ which depends only on $\epsilon$ and the statistics of $V_i$.

**Proof.** See appendix C. □

This lemma allows us to express the limiting SIR in terms of only the eigenvalue distribution of $K_z$.

**Lemma 4.3** As $L, M \to \infty$, $\frac{M}{L} \to \alpha$, the SIR $\beta_1^{(L)}$ converges to

$$\int_0^\infty \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda)$$

in probability, where $G^*$ is the limiting eigenvalue distribution of the random matrix $S_1 D_1 S_1^\dagger$.

**Proof.** See appendix C. □

Call the limit $\beta_*$. We shall now complete the proof of the main theorem by evaluating this limit.

Consider the Stieltjes transform of the limiting spectrum $G^*$ of the matrix $S_1 D_1 S_1^\dagger + \sigma^2 I$:

$$m_{G^*}(z) = \int_0^\infty \frac{1}{\lambda - z} dG^*(\lambda) \quad z \in \mathbb{C}^+.$$
By Theorem 4.1, this satisfies:

\[ m_{G^*}(z) = \frac{1}{z + \alpha \int \frac{PdF(p)}{1 + \frac{P}{P_1}} dF(z)} \]  

(11)

where \( F \) is the limiting distribution of the received powers of the users.

Since the support of \( G^* \) is on the non-negative real axis, \( m_{G^*} \) is continuous in the neighborhood of \( z = -\sigma^2 \). It follows that

\[ \lim_{z \to -\sigma^2} m_{G^*}(z) = \int_0^\infty \frac{1}{\lambda + \sigma^2} dG^*(\lambda) = \frac{\beta_1^*}{P_1} \]

By the continuity of the righthand side of eqn. (11) as a function of \( m_{G^*}(z) \), it follows that

\[ \frac{\beta_1^*}{P_1} = \frac{1}{\sigma^2 + \alpha \int_0^\infty \frac{PdF(p)}{P_1 + \frac{P_1}{P}} dF(z)} \]

Hence the limiting SIR for user 1 satisfies:

\[ \beta_1^* = \frac{P_1}{\sigma^2 + \alpha \int_0^\infty \frac{P_1 PdF(p)}{P_1 + P_1 \beta_1^*}} \]

which completes the proof of the theorem.

While the above provides a rigorous proof, it provides little intuition as why Theorem 3.1 is true. In particular, a better understanding of the decoupling phenomenon between interferers is desired. Based on some new results obtained in [19], we provide a heuristic but more intuitive derivation of formula (4) in Appendix A, bypassing the mysterious Steltjes transform characterization of the limiting eigenvalue distribution of random matrices in (10) and only basing ourselves on Lemma 4.3.

## 5 Capacity and Performance under Power Control

We observed in Section 3 that in the conventional receiver case, the interference of a user is proportional to its power, and hence a strong interferer can completely overcome a weaker signal. This is the so-called near-far problem, and a well-known consequence is that the conventional receiver can only avoid this via tight power control. We also observed, that the MMSE receiver does not suffer arbitrarily poorly from the near-far problem, and indeed this is one of the key motivations for the original work on multiuser detection [16]. Nevertheless, a MMSE receiver still suffers interference from other users, and it follows that capacity can be increased and power consumption reduced, if power control is employed.
In the present section we consider the case in which all users require an SIR of exactly \( \beta^* \), given a processing gain of \( L \) degrees of freedom per symbol. For a given number of users we compute the minimum power consumption required to achieve \( \beta^* \) for all users, and then look at the maximum number of users per degree of freedom supportable for a given power constraint under power control. Of particular interest is the maximum number without power constraint, which we define to be the capacity of the system (in terms of number of users per degree of freedom.) This is the point at which saturation occurs as we put in so many users that we drive the required power level to infinity. We will show that this capacity is different but finite for both the conventional and the MMSE receivers, thus both are interference-limited systems. As before, our results are asymptotic as the processing gain \( L \) goes to infinity.

Let us focus first on the conventional receiver. Under the matched filter, Prop. 3.3 tells us that asymptotically, users receive the same level of interference, and hence must be received at the same power level to get the same SIR \( \beta^* \). It is easy to compute that with a processing gain of \( L \) and \( L \alpha \) users, the common received power required for the conventional receiver asymptotically as \( L \to \infty \) is given by

\[
P_{mf}(\beta^*) = \frac{\beta^* \sigma^2}{1 - \alpha \beta^*}
\]

For a given constraint \( P \) on the received power, the maximum number of users supportable is then:

\[
\frac{1}{\beta^* - \sigma^2/P} \text{ users/degree of freedom}
\]

The capacity of the conventional receiver when \( P = \infty \) is then

\[
C_{mf}(\beta^*) = \frac{1}{\beta^*} \text{ users/degree of freedom}
\]

Put it another way, as \( \alpha \to \frac{1}{\beta^*} \), the system saturates and the required power level goes to infinity. A similar result is given in [3].

Now let us turn to the MMSE receiver. To satisfy given target SIR requirements for each user, [5, 15] showed that there is an optimal solution for which the received power of every user is minimized; moreover, they gave an iterative algorithm to compute it. However, here we can give an explicit solution and characterize the resulting system capacity.

To begin, we fix the number of users per degree of freedom at \( \alpha \). As in the conventional receiver case, it turns out that the system saturates if \( \alpha \) is too high, so we first obtain a necessary and sufficient condition for feasibility. The following theorem shows that in the limit of a large number of degrees of freedom, the system is feasible if and only if the SIR can be met with equal received powers for all users.

**Theorem 5.1** If

\[
\alpha \geq \frac{1 + \beta^*}{\beta^*}
\]
then there is no distribution $F$ of received powers such that the SIR requirements of all users are satisfied, i.e.:

$$\frac{Q}{\sigma^2 + \alpha \int_{0}^{\infty} I(P, Q, \beta^*)dF(P)} \geq \beta^* \quad \text{for all } Q \text{ in the support of } F \quad (14)$$

On the other hand, if $\alpha < \frac{1+\beta^*}{\beta^*}$, the SIR requirements of all users can be satisfied and the minimum power solution is having the received powers of all users to be

$$P_{\text{mmse}}(\beta^*) = \frac{\beta^* \sigma^2}{1 - \alpha \frac{\beta^*}{1+\beta^*}} \quad (15)$$

**Proof.** Suppose that there is a power distribution $F$ such that all users get $\beta^*$, i.e.

$$\frac{Q}{\sigma^2 + \alpha \int_{0}^{\infty} I(P, Q, \beta^*)dF(P)} \geq \beta^* \quad \text{for all } Q \text{ in the support of } F$$

Let $P^*$ be the power of the weakest user in this distribution, i.e.

$$P^* = \inf\{P : F(P) > 0\}$$

and note that $\forall P \geq P^*, I(P^*, P^*, \beta^*) \leq I(P, P^*, \beta^*)$. Focusing on the user with received power $P^*$, since

$$\frac{P^*}{\sigma^2 + \alpha \int_{0}^{\infty} I(P^*, P^*, \beta^*)dF(P)} \geq \beta^*$$

therefore

$$\frac{P^*}{\sigma^2 + \alpha I(P^*, P^*, \beta^*)} \geq \beta^*$$

Using the explicit expression for the effective interference term and rearranging terms, the last statement is equivalent to:

$$P^*(1 - \alpha \frac{\beta^*}{1+\beta^*}) \geq \beta^* \sigma^2$$

Hence,

$$\alpha < \frac{1+\beta^*}{\beta^*}$$

This proves the first part of the proposition.

Conversely, if $\alpha > \frac{1+\beta^*}{\beta^*}$, then it can be easily checked that $P_{\text{mmse}}(\beta^*)$ is positive and satisfies

$$\frac{P_{\text{mmse}}(\beta^*)}{\sigma^2 + \alpha I(P_{\text{mmse}}(\beta^*), P_{\text{mmse}}(\beta^*), \beta^*)} = \beta^*$$

By Theorem 3.1, this implies that by assigning all users the same received power $P_{\text{mmse}}(\beta^*)$, they will all achieve the SIR requirement $\beta^*$. To see that this is the minimal
solution, suppose that $F$ is another power distribution such that the SIR requirements of all users are satisfied, and let $P^*$ be the power of the weakest user of this distribution. By exactly the same argument as the proof of the first half of this proposition, we conclude that:

$$P^* \geq \frac{\beta^* \sigma^2}{1 - \alpha \frac{\beta^*}{\beta^* + \sigma^2}} = P_{\text{mmse}}(\beta^*)$$

This shows that indeed the solution with equal received powers at $P_{\text{mmse}}(\beta^*)$ is the minimal solution.

$\square$

Hence, the capacity of the system under MMSE receiver is:

$$C_{\text{mmse}}(\beta^*) = 1 + \frac{1}{\beta^*} \text{ users/degree of freedom.} \quad (16)$$

Moreover, for a given received power constraint $P$, the maximum number of users that can be supported is to assign each user the same received power, and that number is given by:

$$(1 + \beta^*) \left( \frac{1}{\beta^*} - \frac{\sigma^2}{P} \right) \text{ users/degree of freedom.}$$

Contrasting (12) and (13) with (15) and (16), we note that if $\alpha$ is feasible for both types of receiver, then the MMSE power consumption is less than the matched filter power consumption, and the MMSE has potentially much greater capacity. Indeed, if $\alpha < 1$ then we can take $\beta^*$ arbitrarily high without saturating the MMSE receiver, whereas the conventional receiver saturates at $\beta^* \uparrow \frac{1}{\alpha}$. For fixed $\beta^*$, we also note that the MMSE saturates at a higher value of $\alpha$, yielding a capacity of precisely 1 more user per degree of freedom than the conventional receiver. On the other hand, the relative gain of the MMSE is not so large for small values of $\beta^*$.

The above capacity results are derived in the context of random spreading sequences. A natural question to ask is whether one can get performance gain if we could optimize the choice of the sequences. In [19], it is shown that even with the optimal choice of sequences, the capacity (without power constraint) under the MMSE receiver is still $1 + \frac{1}{\beta^*}$ users per degree of freedom. However, somewhat surprisingly, the capacity gap between the MMSE and conventional receiver disappears under optimal sequences.

6 Multiple classes, maximum power constraints, and effective bandwidths

It is straightforward to generalize our results to the case in which we have $J$ classes, with class $j$ users requiring a SIR of $\beta_j$. We denote the number of users of class $j$ by $\alpha_j L$, and
again consider the limiting regime $L \uparrow \infty$.

The conventional matched filter results generalize very easily to

$$P_{mf}(j) = \frac{\beta_j \sigma^2}{1 - \sum_{j=1}^{J} \alpha_j \beta_j}$$

where $P_{mf}(j)$ denotes the common received power level of all users of class $j$ (see [3]). Thus, the capacity constraint on feasible values of $(\alpha_1, \ldots, \alpha_J)$ is the linear constraint

$$\sum_{j=1}^{J} \alpha_j \beta_j < 1.$$ 

Furthermore, if class $j$ users have a maximum power constraint that $P_{mf}(j) \leq \bar{P}_j$, for each $j$, then the tighter capacity constraint:

$$\sum_{j=1}^{J} \alpha_j \beta_j \leq \min_{1 \leq i \leq J} \left[ 1 - \frac{\beta_i \sigma^2}{\bar{P}_i} \right]$$

emerges ([2]). It seems very reasonable to call $\beta_j$ the bandwidth of class $j$ users, in degrees of freedom per class $j$ user. Let us denote this bandwidth by

$$e_{mf}(\beta_j) = \beta_j \text{ degrees of freedom per class } j \text{ user.}$$

We now show that the MMSE filter results generalize in a similar manner. It is clear in this case also that the minimal power solution consists of the same received power for each class; let all users in class $j$ be received at power $P_j$. Then the power control equations become

$$\frac{P_j}{\sigma^2 + \sum_{i=1}^{J} \alpha_j I(P_i, P_j, \beta_j)} = \beta_j \quad j = 1, 2, \ldots, J \quad (17)$$

where, as in Theorem 3.1, $I(P_i, P_j, \beta_j) \equiv \frac{P_i P_j}{P_i + P_j \beta_j}$. But (17) implies that $\frac{\beta_j}{P_j}$ is a constant, which allows us to simplify (17) down to

$$P_{mmse}(i) = \frac{\beta_i \sigma^2}{1 - \sum_{j=1}^{J} \alpha_j \frac{\beta_j}{1 + \beta_j}} \quad i = 1, 2, \ldots, J. \quad (18)$$

The capacity constraint for the MMSE receiver with $J$ classes is therefore given by

$$\sum_{j=1}^{J} \alpha_j \frac{\beta_j}{1 + \beta_j} < 1 \quad (19)$$

which is linear in $\alpha_1, \ldots, \alpha_J$.

As above, maximum power constraints provide tighter capacity constraints, and in this context we note that (18) implies that

$$\sum_{j=1}^{J} \alpha_j \frac{\beta_j}{1 + \beta_j} = 1 - \frac{\beta_i \sigma^2}{P_{mmse}(i)} \quad i = 1, 2, \ldots, J.$$
Thus if \( P_{mmse}(i) \leq \hat{P}_i \) is a maximum power constraint on class \( i \), then the linear constraint
\[
\sum_{j=1}^{J} \alpha_j \frac{\beta_j}{1 + \beta_j} \leq \min_{1 \leq i \leq J} \left[ 1 - \frac{\beta_i \sigma^2}{\hat{P}_i} \right] \quad i = 1, 2, \ldots, J
\]
defines the restricted capacity region of the system. It seems very reasonable to define the effective bandwidth of class \( j \) users to be \( e_{mmse}(\beta_j) \) degrees of freedom per user, where
\[
e_{mmse}(\beta_j) \equiv \frac{\beta_j}{1 + \beta_j}.
\]

Linearity in the matched filter case is a straightforward consequence of the fact that powers of interferers add. However, our MMSE effective bandwidth results are rather surprising, and it is a consequence of the asymptotic decoupling of the interference due to other users. For more discussions about the linearity of the capacity region under MMMSE, please consult Appendix A.

Fig. 3 gives an example of a capacity region for two classes of users, one with SIR requirement 1dB and the other 10 dB. The upper line gives the asymptotic limit for the boundary of the region, under the MMSE receiver. The simulation curve gives the average number of class 2 users admissible as a function of the number of class 1 users in the system, for a spreading length of 64. The average number is obtained by averaging over 100 realizations of the spreading sequences. The actual number of class 2 users depend on the realization of the spreading sequences, and will fluctuate around this average, as was seen in Fig. 1.

One interesting observation is that no matter how high \( \beta \) is, the MMSE effective bandwidth of a user is upper bounded by unity. We will gain further insight into why this is so in the next section.

7 The Decorrelator

To this point we have contrasted the performance of the MMSE receiver with that of the conventional matched filter receiver. It is also illuminating to compare its performance with that of the decorrelator.

The decorrelator was in fact the first linear “multi-user detector” introduced by Lupas and Verdu [6]. This receiver is known to be optimal in the worst case scenario in which interferers’ powers tend to infinity; its near-far resistance is optimal [7]. Its main shortcoming, as we will see, is that each user has an effective bandwidth of 1 degree of freedom, which can be wasteful when the SIR of the user is small. On the other hand, it is hardly wasteful when the SIR is large.

We can write the channel equation (1) in matrix form:
\[
Y = SX + W
\]
Figure 3: Capacity region for two classes of users, with $\frac{P_1}{\sigma^2} = 29dB$, $\frac{P_2}{\sigma^2} = 20dB$
where $X = (X_1, \ldots, X_M)^t$, and $S = [s_1, \ldots, s_M]$ is the matrix of signature sequences. It is well known ([6]) that the matched filter outputs

$$R = S^t SX + S^t W$$

are sufficient statistics to recover the inputs $X$.

Consider now a further linear transformation applied to the matched filter outputs, to obtain

$$U = (S^t S)^{-1} R = X + (S^t S)^{-1} S^t W$$

The overall filter $(S^t S)^{-1} S^t$ is called the decorrelating receiver. If the inverse does not exist, then the pseudoinverse is used in its place. Observe that in the absence of external noise the decorrelator output would be the vector $X$, and as such it represents the optimal zero-forcing linear filter. At this point, it is useful to provide an expression for the covariance matrix $\Sigma$ of the “noise” $(S^t S)^{-1} S^t W$, namely

$$\Sigma = (S^t S)^{-1} \sigma^2$$

The decorrelator for the user $i$ returns $U_i$ as an estimate of $X_i$. Thus, the channel for user $i$ is given by

$$X_i \rightarrow X_i + N_i$$

where $N_i$ is a zero-mean, Gaussian random variable of variance $\Sigma[i, i]$. The SIR for user $i$ is given by $\frac{\beta_i^{(L)}}{\Sigma[i, i]}$. An important point about the decorrelator detector is that the correlation between the noise variables $(N_i)_{i=1}^L$ is not exploited, which explains why it is suboptimal.

We now study the performance of the decorrelator in the asymptotic regime in which the processing gain $L$ tends to infinity, the number of users is $\alpha L$,

**Theorem 7.1** Let $\beta_1^{(L)}$ be the (random) SIR of the decorrelating receiver for user 1 when the spreading length is $L$. Then $\beta_1^{(L)}$ converges to $\beta_1^*$ in probability as $L \to \infty$, where $\beta_1^*$ is given by

$$\beta_1^* = \begin{cases} \frac{\beta_1^{(1-\alpha)}}{\sigma} & \alpha < 1 \\ 0 & \alpha \geq 1 \end{cases}$$

**Proof.** We begin with the assumption that $\alpha < 1$, and prove convergence of $\Sigma[1, 1]$ to $\frac{\sigma^2}{1-\alpha}$. This implies that the random SIR of user 1 converges to the desired deterministic value.

First, Bai and Yin [1] shows that for $\alpha < 1$, the smallest eigenvalue of $S^t S$ converges almost surely to a positive value. Thus, without loss of generality, we can restrict ourselves to invertible $S^t S$.

$$\Sigma[1, 1] = \frac{1}{\det(S^t S)} \text{Adj}(S^t S)[1, 1] \sigma^2 = \frac{\Delta_M-1(s_2|s_3|\ldots|s_M)}{\Delta_M(s_1|s_2|\ldots|s_M)} \sigma^2$$
where \( \Delta(K') = \det (K'K) \), and \( M \equiv \alpha L \). Further, from the definition of the determinant, we can express the inverse of this ratio of determinants as

\[
\frac{\Delta_M(s_1|s_2|\ldots|s_M)}{\Delta_{M-1}(s_2|s_3|\ldots|s_M)} = s_1^T \tilde{K}s_1
\]

where \( \tilde{K} \) is a non-negative, symmetric, \( L \times L \) matrix that only depends on the vectors \( s_2, s_3, \ldots, s_M \). It follows that there exists an orthonormal matrix \( Q \), such that

\[
\Sigma[1, 1]^{-1} = u^T \Omega u
\]

where \( u \equiv QS_1 \), and \( \Omega \) is diagonal.

This approach has been taken for a similar antenna array problem in [20], and there, in the Theorem in Appendix A, it is shown that \( \tilde{K} \) has exactly \( M - 1 \) eigenvalues equal to 0, and \( L - M + 1 \) eigenvalues equal to 1. Thus we can take the first \( L - M + 1 \) diagonal elements of \( \Omega \) to be unity, and the rest 0.

Let \( \tilde{Q} \) be the \( (L - M + 1) \times L \) matrix consisting of the first \( L - M + 1 \) rows of \( Q \). If we define the \( L - M + 1 \) dimensional vector \( \tilde{u} \) by

\[
\tilde{u} \equiv \sqrt{L} \tilde{Q}s_1
\]

then Lemma 4.2 gives us that

\[
\frac{\|\tilde{u}\|^2}{L} \to (1 - \alpha) \quad \text{in probability as} \quad L \uparrow \infty.
\]

It follows that \( (\tilde{\Sigma}[1, 1])^{-1} \) converges in probability to \( \frac{1 - \alpha}{\sigma^2} \).

Finally, we observe that as \( \alpha \uparrow 1 \), the limiting SIR tends to zero. But the SIR cannot increase with increasing \( \alpha \), and is bounded below by 0, so the limiting SIR must be zero when \( \alpha \geq 1 \).

We observe that as \( \alpha \to 1 \), i.e. the number of users per degree of freedom approach 1, the SIR goes to zero. Geometrically, as the dimensionality of the orthogonal complement to the span of the interference decreases to zero, the length of the projection of the desired signal onto this orthogonal complement tends to zero, and so in the limit the projected signal is lost in the background noise. This is the high price paid for ignoring the background noise. In contrast, the MMSE receiver can support more users than the number of degrees of freedom as it takes both the interference and the background noise into account. In Appendix B, we will give a second derivation of Theorem 7.1 which will emphasize this geometric interpretation.

By comparing Theorem 7.1 and Theorem 3.1, it can be seen that the effective interference for an interferer on user 1 under the decorrelator is \( \frac{P_i}{\beta_i} \), which does not depend on the power of the interferer. The theorem states that the capacity constraint on the system is \( \alpha < 1 \).
We also observe that if all users require an SIR of $\beta$ and employ power control then it is sufficient for each user to be received with power at least $\frac{\beta \sigma^2}{1 - \alpha}$. Thus, for a given received power constraint $\bar{P}$, the maximum number of users with SIR requirement $\beta$ supportable is $1 - \frac{\beta \sigma^2}{\bar{P}}$. Similarly, for multiple classes of users with SIR requirement $\beta_j$ and power constraint $\bar{P}_j$ for each class, then the system can support $\alpha_j$ users (per degree of freedom) from each class if

$$\sum_{j=1}^J \alpha_j \leq \min_{1 \leq i \leq J} \left[ 1 - \frac{\beta_j \sigma^2}{\bar{P}_j} \right]$$

Thus, the capacity region under the decorrelator is given by:

$$\sum_{j=1}^J \alpha_j \leq 1 \quad (20)$$

when there are no power constraints, or equivalently, when the background noise power $\sigma^2$ goes to zero. Thus, each user occupies an effective bandwidth of 1 degree of freedom, independent of the value of $\beta$.

From Theorem 7.1, it can be immediately inferred that the efficiency of a decorrelator in a large system with random spreading sequences is $1 - \alpha$ if $\alpha$, the number of users per degree of freedom, is less than 1 and zero otherwise. Since this does not depend on the background noise power $\sigma^2$, this is also the asymptotic efficiency.

It is well known [8] that the MMSE receiver has the same asymptotic efficiency as the decorrelator, and hence the decorrelator is optimal in this sense among all linear receivers. However, comparing eqn. (19) and (20), it can be seen that the capacity region under the MMSE receiver is strictly larger than that under the decorrelator, even as the background noise goes to zero. In particular, the MMSE receiver can in general accommodate more users than the available degrees of freedom, while the decorrelator cannot. This apparent paradox can be resolved by noting that when $\alpha > 1$, the attained SIR by the decorrelator is zero (Theorem 7.1) while the attained SIR by the MMSE receiver is strictly positive but bounded, as the noise power $\sigma^2$ goes to zero. Since the asymptotic efficiency only measures the rate at which the SIR goes to infinity as $\sigma^2$ goes to zero, they are the same (zero) for both receivers. On the other hand, the capacity region quantifies the number of users with fixed SIR requirements a receiver can accommodate; hence the difference between the decorrelator and the MMSE receiver is reflected. In practice, users have target SIR requirements and hence the capacity region characterization seems to be a more natural performance measure than the asymptotic efficiency. In this context, the decorrelator remains sub-optimal even as $\sigma^2 \to 0$.

8 Antenna Diversity

In spread-spectrum systems, diversity gain is obtained by spreading over a wider bandwidth. However, there are other ways to obtain diversity benefits in a wireless system. A
technique, particularly effective for combating multipath fading, is the use of an adaptive antenna array at the receiver. Multipath fading can be very detrimental as the received signal power can drop dramatically due to destructive interference between different paths of the transmitted signal. By placing the antenna elements greater than half the carrier wavelength apart, one can ensure that the received signal fades more or less independently at the different antenna elements. By appropriately weighing, delaying and combining the received signals at the different antenna elements, one can obtain a much more reliable estimate of the transmitted signal than with a single antenna. Such antenna arrays are said to be adaptive as the combining depends on the strengths of the received signals at the various antenna elements. This in turn depends on the location of the users. Moreover, the combining weights will be different for different users, allowing the array to focus on specific users while mitigating the interference from other users. This is so-called beam-forming. Using our previous results, it turns out that the capacity of such antenna array system can again be characterized by effective bandwidths.

The following is a model for a synchronous multi-access antenna-array system:

\[ Y = \sum_{m=1}^{M} X_m h_m + W, \]

Here, \( X_m \) is the transmitted symbol of the \( m \)th user, and \( Y \) is a \( L \)-dimensional vector of received symbols at the \( L \) antenna elements of the array. The vector \( h_m \) represents the fading of the \( m \)th user at each of the antenna array. The entries are complex to incorporate both phase and magnitude information. The vector \( W \) is \( N(0, \sigma^2 I) \) background Gaussian noise.

The fading is time-varying, as the mobile users move. However, this is usually at a much slower time-scale than the symbol rate of the system. Assuming then that the channel fading of the users can be measured and tracked perfectly at the receiver, we would like to combine the vector of received symbols appropriately to maximize the SIR of the estimates of the transmitted symbols of the users. The optimal linear receiver is clearly the MMSE. Assuming that the fading of each user at each antenna element is independent and identically distributed, we are essentially in the same set-up as for spread-spectrum systems. Thus, for a system with large number of antenna elements and large number of users, we can treat each of the interfering users as contributing an additive effective interference. Under perfect power control, the system capacity is characterized by sharing the \( L \) degree of freedom among the users according to their effective bandwidths given by the previous expressions for the different receivers. The only difference here is that the \( L \) degrees of freedom is obtained by spatial rather than frequency diversity.

These results should be compared with that of Winters et. al. [20], which showed that for a flat Rayleigh fading channel, a combiner which attempts to null out all the interferers will cost one degree of freedom per interferer. This combiner is of course the sub-optimal decorrelator, which we have shown earlier to be very wasteful of degrees of freedom if interferers are weak. It should be noted that while Winters' result holds for the Rayleigh model and any number of antennas, our results hold for any fading distribution,
but are asymptotic in the number of antennas.

Fig. 4 illustrates the performance of MMSE receiver under a Rayleigh fading environment. It compares the asymptotic limit of the SIR for user 1 given by eqn. 8, as a function of the number of users per antenna elements, with actual SIR achieved depending on realizations of the Rayleigh fading. The number of antenna elements is 128. The similarity between Fig. 4 and Fig. 1 further emphasizes the fact that the asymptotic limit does not depend on the interpretation of the $s_i$'s as spreading sequences or as channel fading.

9 Summary of Results and Conclusions

It is illuminating to compare the effective interference and effective bandwidths of the users in the three cases: the conventional matched filter, the MMSE filter, and the decorrelating filter (Fig. 5 and 6). The effective interference under MMSE is non-linear, and depends on the received power $P$ of the user to be demodulated as well as the achieved SIR $\beta$. The effective interference under the conventional matched filter is simply $P$, the received power of the interferer. Under the decorrelator, the effective interference is $\frac{P}{\beta}$, independent of the actual power of the interferer. The intuition here is that the decorrelator completely nulls out the interferer, no matter how strong or weak it is.

Assuming perfect power control, we can define effective bandwidths which characterize the amount of network resource a user consumes for a given target SIR. The effective bandwidths under the conventional, MMSE and decorrelating receivers are $\beta_1 \frac{\beta}{1+\beta}$ and 1 respectively. We note that the conventional receiver is more efficient than the decorrelator when $\beta$ is small, and far less efficient when $\beta$ is large. Intuitively, at high SIR requirements, a user has to transmit at high power, thus causing a lot of interference to other users under the conventional receiver. Not surprisingly, since it is by definition optimal, the MMSE filter is the most efficient in all cases. When $\beta$ is small, it operates more like the conventional receiver, allowing many users per degree of freedom, but when $\beta$ is large, each user is decorrelated from the rest, much as in the decorrelator receiver, and therefore the interferers can still occupy no more than 1 degree of freedom per interferer. The performance gain afforded by the MMSE receiver over the conventional receiver depends on the SIR at which the system is to be operated, and this in turn depends on the data rate, amount of coding and symbol constellation size. However, due to the superior performance of the MMSE receiver over a wide range of SIR's, it can be seen that it is particularly suitable in a heterogeneous network with multiple traffic types.

While the effective bandwidth results provide much insight into the performance of these filters, it must be emphasized that they pertain only to a single cell, without multi-path fading, and in the symbol-synchronous case. It remains to be seen how these filters perform in more realistic scenarios. The multi-cell scenario is particularly important to be studied. While the effective bandwidth concept for the MMSE receiver is only valid in the perfectly power-controlled case, the concept of effective interference applies with or without perfect power control, and may prove more useful in the multi-cell context.
Figure 4: Random SIR's for user 1 in Rayleigh fading environment, compared to asymptotic limit eqn. (8) Here, $\frac{P}{\sigma^2} = 20dB$. 
Figure 5: Effective interference for the 3 receivers as a function of interferer's received power $P_i$. Here, $P$ is the received power of the user to be demodulated, and $\beta$ is the SIR achieved.

Figure 6: Effective bandwidths for 3 receivers as a function of SIR.
In a TDMA or FDMA system, the network resource is shared among users via disjoint frequency and time slots, and they provide a simple abstraction of the resource consumed by a user at the physical layer. Such an abstraction allows a clean separation between the physical layer and networking layer resource allocation problems, such as call admissions control, cell handoffs and resource allocation for bursty traffic. It is hope that the effective bandwidth results presented here will be a first step in providing such an abstraction for systems with multiuser receivers.

10 Acknowledgments

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References


Appendices

A  A Heuristic Derivation of Theorem 3.1

In this appendix, we gave an alternative and heuristic derivation of expression (4), without invoking the Steltjes transform characterization of the limiting eigenvalue distribution (10). The goal is to shed more light into the form of the expression and to provide some intuition about the decoupling of the interference from different users and the consequent linearity in the effective bandwidth characterization of the capacity region. The derivation given here makes use of some ideas developed in [19] but is self-contained.

We first give a formula for the MMSE receiver and the associated SIR under the MMSE receiver, alternative but equivalent to (2) and (3). First recall the channel model in matrix form:

\[ Y = SX + W \]

where \( S \) is the matrix the columns of which are the signature sequences of the users. If \( \hat{X} \) is the vector MMSE estimate of \( X \), a direct application of the orthogonality principle \( E[(\hat{X} - X)'Y] = 0 \) yields

\[ \hat{X} = DS^t \left[ SDS^t + \sigma^2 I \right]^{-1} \]

and the covariance matrix of the error \( e \equiv \hat{X} - X \) is given by

\[ K_i = D - DS^t \left[ SDS^t + \sigma^2 I \right]^{-1} SD \]  \hspace{1cm} (21)

where \( D \equiv \text{diag}(P_1, \ldots, P_M) \) is the covariance matrix of \( X \). Right multiplying the above equation with \( D^{-1} \) and taking the trace of both sides, we get:

\[
\begin{align*}
\text{trace}(K_i D^{-1}) & = M - \text{trace} \left( DS^t \left[ SDS^t + \sigma^2 I \right]^{-1} S \right) \\
& = M - \text{trace} \left( SDS^t \left[ SDS^t + \sigma^2 I \right]^{-1} \right) \text{ using the fact } \text{trace}(AB) = \text{trace}(BA) \\
& = M - \sum_{i=1}^{L} \frac{\lambda_i}{\lambda_i + \sigma^2} \hspace{1cm} (23)
\end{align*}
\]

where \( \lambda_i \)'s are the eigenvalues of the matrix \( SDS^t \). If we let

\[ \text{MMSE}_i \equiv \frac{E[(\hat{X} - X_i)^2]}{P_i} \]

be the (normalized) minimum mean-square error for user \( i \), then eqn. (23) says that

\[ \sum_{i=1}^{M} \text{MMSE}_i = M - \sum_{i=1}^{L} \frac{\lambda_i}{\lambda_i + \sigma^2} \hspace{1cm} (24) \]
Now it is well known that the SIR $\beta^{(L)}_i$ and the MMSE error are related as follows (see e.g. [8]):

$$\text{MMSE}_i = \frac{1}{1 + \beta^{(L)}_i}. \quad (25)$$

Substituting this into eqn. (24) and rearranging terms, we obtain,

$$\frac{1}{L} \sum_{i=1}^{M} \frac{\beta^{(L)}_i}{1 + \beta^{(L)}_i} = 1 - \sigma^2 \frac{1}{L} \sum_{i=1}^{L} \frac{1}{\lambda_i + \sigma^2} \quad (26)$$

So far, we have not introduced any probabilistic model for the spreading sequences, and this equation holds for every choice of the sequences and for every $L$. Now, let us assume the sequences are randomly chosen, and each component is i.i.d., and consider what happens when $M, L \to \infty$, $\frac{M}{L} \to \alpha$ and the empirical distribution of the received powers converge to $F$. The right-hand side of the above equation converges to

$$1 - \sigma^2 \int_0^\infty \frac{1}{\lambda + \sigma^2} dG^*(\lambda)$$

where $G^*$ is the limiting eigenvalue distribution of $SDS^t$, and by Lemma 4.3, $\beta^{(L)}_i$ converges to

$$\beta_i^* = P_i \int_0^\infty \frac{\lambda}{\lambda + \sigma^2} dG^*(\lambda)$$

Expressing everything in terms of $\beta_i^*$, one can expect that the limiting form of eqn. (26) to become $^3$:

$$\alpha \int_0^\infty \frac{P_i \beta_i^*}{1 + \frac{P_i \beta_i^*}{P_1}} dF(P) = 1 - \frac{\sigma^2 \beta_i^*}{P_1}$$

Dividing throughout by $\frac{P_i \beta_i^*}{P_1}$ and rearranging terms gives us the desired fixed-point equation (4):

$$\beta_i^* = \frac{P_1}{\sigma^2 + \alpha \int_0^\infty \frac{P_i dF(P)}{P_1 + P_i \beta_i^*}}$$

This development allows us to understand the linearity of the effective bandwidth characterization of the capacity region. First, consider the simpler case when $\sigma^2 \to 0$, i.e. no power constraint. Assuming that the spreading sequences span a space of dimension $\min\{M, L\}$. Then precisely $\min\{M, L\}$ of the eigenvalues $\lambda_i$'s are non-zero. Eqn. (24) becomes:

$$\sum_{i=1}^{M} \text{MMSE}_i = M - \min\{M, L\}$$

Note that the total MMSE of the users is a constant, irrespective of the received powers of the users. Since the SIR of a user is a function of the MMSE error, this is the reason

$^3$This is the heuristic step of the derivation.
for the linearity of the capacity region with no power constraint. For the case when there are power constraints (i.e. $\sigma^2 \neq 0$), the situation is more subtle. Asymptotically, the right-hand side of eqn. (24) depends on the received powers of the users only through

$$\int_0^\infty \frac{1}{\lambda + \sigma^2} dG^*(\lambda)$$

which can be interpreted as the SIR achieved by a user with unit received power.

**B Decorrelator Revisited**

Here we give another derivation of the performance of the decorrelator. This derivation has the advantage of providing more geometric insights into the operation of the receiver and also illuminates the relationship between the decorrelator and the MMSE receiver. We start with an alternative definition of the decorrelator, focusing without loss of generality on user 1.

**Definition B.1** The decorrelator receiver for user 1, $\hat{X}_{dec}(\cdot)$, is a linear functional of the received vector $Y$, which maximizes the SIR subject to the constraint that $\hat{X}_{dec}(Y)$ is statistically independent of $X_2, X_3, \ldots, X_M$.

We observe that the decorrelator has the same objective as the MMSE receiver except that the estimate of the symbol of user 1 is further constrained to be independent of the symbols of the other users.

Let $\hat{X}_{dec}(Y) := v^t Y$. Now, expressing in terms of the transmitted symbols and the background noise,

$$\hat{X}_{dec}(Y) = (v^t s_1)X_1 + \sum_{m \neq 1} (v^t s_m)X_m + v^t Z = (v^t s_1)X_1 + v^t Z$$

since it is easy to see that the estimate being independent of $X_2, \ldots, X_M$ is equivalent to the fact that $v^t s_m = 0$ for all $m \neq 1$. Let $V := \text{span}\{s_2, \ldots, s_M\}^\perp$ be a subspace. Noting that $\text{Var}(v^t Z) = \sigma^2 v^t v$, the vector $v$ should be chosen to maximize the SIR

$$\frac{P_1 (v^t s_1)^2}{\sigma^2 v^t v}$$

subject to the constraint that $v \in V$. We shall now show the geometrically intuitive fact that the optimal $v^*$ is along the direction of the projection of $s_1$ onto $V$. Since (27) is invariant to scaling of $v$, we can consider the equivalent optimization problem with the same optimal value:

$$\frac{P_1}{\sigma^2} \max_{u \in V, u^t u = 1} (u^t s_1)^2.$$  \hspace{1cm} (28)

Now,

$$\|s_1 - u\|^2 = s_1^t s_1 + 1 - 2u^t s_1$$
and so the optimal \( u^* \) in (28) is the vector in \( V \) with norm 1 which is closest to \( s_1 \). By the projection theorem, \( u^* \) and hence \( v^* \) is along the projection of \( s_1 \) onto \( V \). If \( w \) is the projection of \( s_1 \) onto \( V \), then the SIR of the decorrelator is given by:

\[
\beta_1 = \frac{P_1 (w^* s_1)^2}{\sigma^2} = \frac{P_1 (w^* (s_1 - w + w))^2}{\sigma^2 w^* w} = \frac{P_1}{\sigma^2} w^* w
\]

by the orthogonality principle.

Consider now the situation when the signature sequences are chosen randomly and independently, with \( M < L \). The subspace \( V \) depends only on the signature sequences \( s_2, \ldots, s_M \) and therefore independent of \( s_1 \). Moreover as \( L \to \infty \), with high probability it has dimension \( \max\{L - M + 1, 0\} \). Lemma 4.2 then implies that \( w^* w \to 1 - \alpha \) in probability, as \( L, M \to \infty \) and \( \frac{M}{L} \to \alpha \), if \( \alpha < 1 \). If \( \alpha \geq 1 \), then \( w^* w \to 0 \) in probability. This proves Theorem 7.1.

C Proofs

Proof of Proposition 3.3:

Now,

\[
\beta^{(L)}_{1,M,F} = \frac{P_1 (s_i^* s_1)^2}{\sigma^2 (s_i^* s_1)^2 + \sum_{i=2}^{M} P_i (s_i^* s_i)^2}.
\]

Clearly \( (s_i^* s_1)^2 \) converges to 1 in probability, by the weak law of large numbers. We now look at the interference from the other users. Set

\[
\xi_i = \frac{1}{\sqrt{L}} \sum_{k=1}^{L} V_{1,k} V_{i,k} \quad i = 1, 2, \ldots, M
\]

where \( s_i = \frac{1}{\sqrt{L}}(V_{i1}, \ldots, V_{iL})' \). Also, define \( \bar{P}^{(M)} = \frac{1}{M} \sum_{i=1}^{M} P_i \). Let us first condition on a random realization of powers \( P_1, P_2, \ldots \). Then

\[
\text{Var} \left( \sum_{i=2}^{M} P_i \xi_i^2 | P_1, P_2, \ldots \right) = \sum_{i=2}^{M} \sum_{j=2}^{M} \mathbb{E} \left[ \left( \frac{P_i}{L} (\sum_{k_1} V_{1,k_1} V_{i,k_1})^2 - \bar{P}^{(M)} \right) \left( \frac{P_j}{L} (\sum_{k_2} V_{1,k_2} V_{j,k_2})^2 - \bar{P}^{(M)} \right) \right] \]

By expanding out the product, we obtain that for \( i \neq j \), the term

\[
\mathbb{E} \left[ \left( \frac{P_i}{L} (\sum_{k_1} V_{1,k_1} V_{i,k_1})^2 - \bar{P} \right) \left( \frac{P_j}{L} (\sum_{k_2} V_{1,k_2} V_{j,k_2})^2 - \bar{P} \right) \right] \]

equals

\[
\frac{P_i P_j}{L^2} \mathbb{E}[(\sum_{k} V_{1,k} V_{i,k})^2 (\sum_{k} V_{1,k} V_{j,k})^2] - \frac{\bar{P} P_j}{L} \mathbb{E}[(\sum_{k} V_{1,k} V_{j,k})^2] - \frac{\bar{P} P_i}{L} \mathbb{E}[(\sum_{k} V_{1,k} V_{i,k})^2] + \bar{P}^2 \quad (30)
\]
Expanding out the first term on the right hand side, we obtain

$$\sum_{k_1} \sum_{k_2} \sum_{k_3} \sum_{k_4} \mathbb{E}[V_{i,k_1} V_{i,k_3}] \mathbb{E}[V_{j,k_2} V_{j,k_4}] \mathbb{E}[V_{i,k_1} V_{i,k_2} V_{i,k_3} V_{i,k_4}]$$

Now each of these expectations is zero except when $k_1 = k_3$ and $k_2 = k_4$, so it reduces to $\sum_{k_1} \sum_{k_2} \mathbb{E}[V_{i,k_1} V_{i,k_2}^2]$. Now, $L(L - 1)$ of these terms are unity, and $L$ are $\mathbb{E}[V_{i,k_1}^4]$, which is $O(1)$, so it follows that the first term on the right hand side of (30) is $P_i P_j + O(1/L)$. In a similar manner, the second term can be shown to be $P_j \tilde{P}$ and the third term is $P_i \tilde{P}$.

Returning to the expansion of (29), we note that for all $i = 2, \ldots, M$,

$$\mathbb{E} \left[ \left( \frac{P_i}{L} (\sum_{k_1} V_{1,k_1} V_{1,k_1})^2 - \tilde{P} \right)^2 | P_1, P_2, \ldots \right]$$

equals

$$\frac{P_i^2}{L^2} \mathbb{E}[\sum_{k_1} V_{1,k} V_{1,k}]^4 - \frac{P_i \tilde{P}}{L} \mathbb{E}[\sum_{k_1} V_{1,k} V_{1,k}]^2 + \tilde{P}^2 \quad (31)$$

Expanding out the first term we obtain

$$\sum_{k_1} \sum_{k_2} \sum_{k_3} \sum_{k_4} \mathbb{E}[V_{1,k_1} V_{1,k_2} V_{1,k_3} V_{1,k_4}] \mathbb{E}[V_{1,k_1} V_{1,k_2} V_{1,k_3} V_{1,k_4}]$$

and each of these expectations is zero, unless $k_1 = k_2$ and $k_3 = k_4$ or $k_1 = k_3$ and $k_2 = k_4$ or $k_1 = k_4$ and $k_2 = k_3$. In each of these nonzero cases, the expectations are $O(1)$ and there are $O(L^2)$ of them, so the first term of (31) is $O(1)$. Similarly, for the other two terms. We conclude that

$$\text{Var} \left( \frac{1}{M} \sum_{i=2}^{M} P_i \xi_i^2 | P_1, P_2, \ldots \right) = \frac{1}{M^2} \sum_{i=2}^{M} \sum_{j=2}^{M} (P_i P_j - P_j \tilde{P}^{(M)} - P_i \tilde{P}^{(M)} + (\tilde{P}^{(M)})^2) + O(1/L)$$
as $L \uparrow \infty$. But by our assumption that the empirical distribution function of powers converges to a deterministic limit, it follows that

$$\frac{1}{M^2} \sum_{i=2}^{M} \sum_{j=2}^{M} (P_i P_j - P_j \tilde{P}^{(M)} - P_i \tilde{P}^{(M)} + (\tilde{P}^{(M)})^2) \to 0$$

and hence that for any $\epsilon > 0, \lim \sup_M \text{Var} \left( \frac{1}{M} \sum_{i=2}^{M} P_i \xi_i^2 | P_1, P_2, \ldots \right) < \epsilon$, and this is true for any realization $P_1, P_2, \ldots$. Hence, for all $\epsilon > 0, \lim \sup_M \mathbb{E}[\left( \frac{1}{M} \sum_{i=2}^{M} P_i \xi_i^2 - \bar{P}(M) \right)^2] < \epsilon$. But $\bar{P}(M) \to \int_{0}^{\infty} PdF(P)$, which implies mean-square convergence of $\frac{1}{M} \sum_{i=2}^{M} P_i \xi_i^2$ to $\int_{0}^{\infty} PdF(P)$, and hence convergence in probability. So we have

$$\sum_{i=2}^{M} P_i (s_i \xi_i)^2 = \frac{1}{L} \sum_{i=2}^{M} P_i \xi_i^2 \to \alpha \int_{0}^{\infty} PdF(P)$$
in probability. We conclude that

$$\beta_{1, MF}^{(L)} \rightarrow \frac{P_1}{\sigma^2 + \alpha \int_0^\infty PdF(P)} \text{ in probability}$$

\[\square\]

**Proof of Lemma 4.2:**

Let \( Y \equiv \|QX\|^2 \). We compute the first and second moments of \( Y \) conditional on an arbitrary realization of \( Q = (q_{ij}) \).

\[
E[Y|Q] = E \left[ \sum_{i=1}^{m} \left( \sum_{j=1}^{n} q_{ij} V_j \right)^2 \right]
\]

\[
= E \left[ \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} q_{ij} q_{ik} V_j V_k \right]
\]

\[
= \sum_{i=1}^{m} \sum_{j=1}^{n} q_{ij}^2
\]

\[
= m,
\]

\[
E[Y^2|Q] = E \left[ \left\{ \sum_{i=1}^{m} \left( \sum_{j=1}^{n} q_{ij} V_j \right) \right\}^2 \right]
\]

\[
= E \left[ \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} \sum_{l=1}^{n} \sum_{r=1}^{n} \sum_{s=1}^{n} q_{ik} q_{il} q_{jr} q_{js} V_k V_l V_r V_s \right]
\]

Since the \( V_i \)'s are independent and zero mean, the terms in the expectation above are zero whenever it has one random variable which has a different index than the other three. Hence,

\[
E[Y^2|Q]
\]

\[
= \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} q_{ik}^2 q_{jk}^2 E[V_k^4] + \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} q_{ik}^2 q_{jr}^2 E[V_r^2] E[V_k^2] + 2 \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} \sum_{l=1}^{n} q_{ik} q_{il} q_{jk} q_{jl} E[V_k^2] E[V_i^2]
\]

\[
= \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} q_{ik}^2 q_{jk}^2 (E[V_k^4] - 3) + \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} q_{ik}^2 q_{jr}^2 + 2 \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} \sum_{l=1}^{n} q_{ik} q_{il} q_{jk} q_{jl}
\]

\[
= \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} q_{ik}^2 q_{jk}^2 (E[V_k^4] - 3) + \sum_{i=1}^{m} \sum_{j=1}^{n} (\sum_{k=1}^{n} q_{ik}^2)(\sum_{r=1}^{n} q_{jr}^2) + 2 \sum_{i=1}^{m} \sum_{j=1}^{n} (\sum_{k=1}^{n} q_{ik} q_{il})^2
\]

\[
= \sum_{k=1}^{n} (\sum_{i=1}^{m} q_{ik}^2)^2 (E[V_k^4] - 3) + m^2 + 2m
\]

the last step using the orthonormality of the rows of \( Q \). Now if we add orthonormal rows to \( Q \) to construct a \( n \) by \( n \) orthogonal matrix \( Q' \), then the columns of \( Q' \) are orthonormal.
This implies that for every column $k$,

$$
\sum_{i=1}^{m} q_{ik}^2 \leq 1
$$

Hence

$$
E[Y^2|Q] \leq n|E[V_1^4] - 3| + m^2 + 2m
$$

and

$$
E[(Y - m)^2|Q] \leq n|E[V_1^4] - 3| + 2m
$$

and hence

$$
E[(Y - m)^2] \leq n|E[V_1^4] - 3| + 2m
$$

Using Chebychev's inequality, we have for every $\epsilon > 0$,

$$
\Pr \left[ \left| \frac{Y}{n} - \frac{m}{n} \right| > \epsilon \right] \leq \frac{E[(Y - m)^2]}{n^2 \epsilon^2} \leq \frac{n|E[V_1^4] - 3| + 2m}{n^2 \epsilon^2} \leq \frac{|E[V_1^4] - 3| + 2}{\epsilon^2} \cdot \frac{1}{n}.
$$

Picking the constant $C \equiv \frac{|E[V_1^4] - 3| + 2}{\epsilon^2}$ yields the desired result.

$\square$

**Proof of Lemma 4.3:**

From eqn. (3),

$$
\beta_1^{(L)} = s_1(S_1 D_1 S_1^t + \sigma^2 I)^{-1}s_1 P_1
$$

Let $\lambda_1^{(L)}, \ldots, \lambda_L^{(L)}$ be the eigenvalues of $S_1 D_1 S_1^t$. Write $S_1 D_1 S_1^t + \sigma^2 I$ as $Q' \Lambda Q$, where $\Lambda = \text{diag}(\lambda_1^{(L)} + \sigma^2, \ldots, \lambda_L^{(L)} + \sigma^2)$. Let $u^{(L)} = Q s_1$. Then

$$
\beta_1^{(L)} = \sum_{i=1}^{L} \frac{[u_i^{(L)}]^2 P_1}{\lambda_i^{(L)} + \sigma^2}
$$

Fix a $\delta_1 > 0$. Pick a finite partition $I = \{I_1, I_2, \ldots, I_K\}$ of $(0, \infty)$ such that

$$
\sum_{k=1}^{K} G^*(I_k) \frac{P_1}{l(I_k) + \sigma^2} - \int_{0}^{\infty} \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) < \delta_1
$$

and

$$
\int_{0}^{\infty} \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) - \sum_{k=1}^{K} G^*(I_k) \frac{P_1}{r(I_k) + \sigma^2} < \delta_1
$$
where \(l(I_k), r(I_k)\) are the left and right endpoints of the interval \(I_k\) respectively.

Let \(G_L\) be the empirical distribution of the eigenvalues of \(S_1D_1S_1^T\). Fix \(\delta_2 > 0\), and consider the events:

\[
E_1 = \left\{ \sum_{(i, \lambda_i^{(L)}) \in I_k} \left( u_i^{(L)} \right)^2 - G_L(I_k) \leq \frac{\delta_2}{K} \text{ for all } k = 1, \ldots, K \right\}
\]

\[
E_2 = \left\{ |G_L(I_k) - G^*(I_k)| < \frac{\delta_2}{K} \text{ for all } k = 1, \ldots, K \right\}
\]

If both events \(E_1\) and \(E_2\) hold, then we have

\[
\beta_1^{(L)} = \sum_{i=1}^L \frac{u_i^{(L)} P_1}{\lambda_i^{(L)} + \sigma^2}
\]

\[
\leq \sum_{k=1}^K \left( \sum_{(i, \lambda_i^{(L)}) \in I_k} \left( u_i^{(L)} \right)^2 \right) \frac{P_1}{l(I_k) + \sigma^2}
\]

\[
\leq P_1 \sum_{k=1}^K \frac{G^*(I_k) + 2 \delta_2}{l(I_k) + \sigma^2}
\]

\[
\leq \int_0^\infty \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) + \delta_1 + \frac{2 \delta_2}{\sigma^2} \quad \text{from eqn. (33)}
\]

and similarly,

\[
\beta_1^{(L)} \geq \sum_{k=1}^K \left( \sum_{(i, \lambda_i^{(L)}) \in I_k} \left( u_i^{(L)} \right)^2 \right) \frac{P_1}{r(I_k) + \sigma^2}
\]

\[
\geq P_1 \sum_{k=1}^K \frac{G^*(I_k) - 2 \delta_2}{l(I_k) + \sigma^2}
\]

\[
\geq \int_0^\infty \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) - \delta_1 - \frac{2 \delta_2}{\sigma^2} \quad \text{from eqn. (33)}
\]

Hence, given any \(\epsilon > 0\), one can pick \(\delta_1, \delta_2 > 0\) and \(K\) such that:

\[
\left| \beta_1^{(L)} - \int_0^\infty \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) \right| < \epsilon
\]

whenever events \(E_1\) and \(E_2\) occur. Thus, by the union of events bound,

\[
\Pr \left[ \left| \beta_1^{(L)} - \int_0^\infty \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) \right| > \epsilon \right] \leq \Pr[E_1^c] + \Pr[E_2^c]
\]

(35)
By Theorem 4.1, each of the probabilities in the sum go to zero as $L \to \infty$. Hence $\Pr[E_2^c] \to 0$. Now,

$$\Pr[E_i^c] = \Pr \left[ \left| \sum_{\{i: \lambda_i^{(L)} \in I_k\}} (u_i^{(L)})^2 - G_L(I_k) \right| > \frac{\delta_2}{K} \right]$$

$$\leq \sum_{k=1}^{K} \Pr \left[ \left| \sum_{\{i: \lambda_i^{(L)} \in I_k\}} (u_i^{(L)})^2 - G_L(I_k) \right| > \frac{\delta_2}{K} \right]$$

$$\leq \frac{C}{L} \quad \text{by Lemma 4.2}$$

$$= \frac{KC}{L}$$

which approaches 0 as $L \to \infty$. Hence, from eqn. (35), we can conclude that

$$\beta_1^{(L)} \to \int_0^{\infty} \frac{P_1}{\lambda + \sigma^2} dG^*(\lambda) \quad \text{in probability.}$$

$\square$